

الوسائط المتعددة و برمجتها

السنة الثالثة

قسم تقنيات الحاسوب

المحاضرة الثانية

إعداد

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Chapter 2

Digital Image Fundamentals

Representing Digital Images

The result of sampling and quantization is a matrix of real numbers.

Suppose that a continuous $f(x,y)$ is approximated by equally spaced samples arranged in the form of an ($M \times N$) array as shown :

$$f(x,y) \cong \begin{array}{|cccc|} \hline f(0,0) & f(0,1) & \dots\dots\dots & f(0,N-1) \\ f(1,0) & f(1,1) & \dots\dots\dots & f(1,N-1) \\ \cdot & \cdot & \dots\dots\dots & \\ \cdot & \cdot & \dots\dots\dots & \\ \cdot & \cdot & \dots\dots\dots & \\ \cdot & \cdot & \dots\dots\dots & \\ f(M-1,0) & f(M-1,1) & \dots\dots\dots & f(M-1,N-1) \\ \hline \end{array}$$

Representing Digital Images

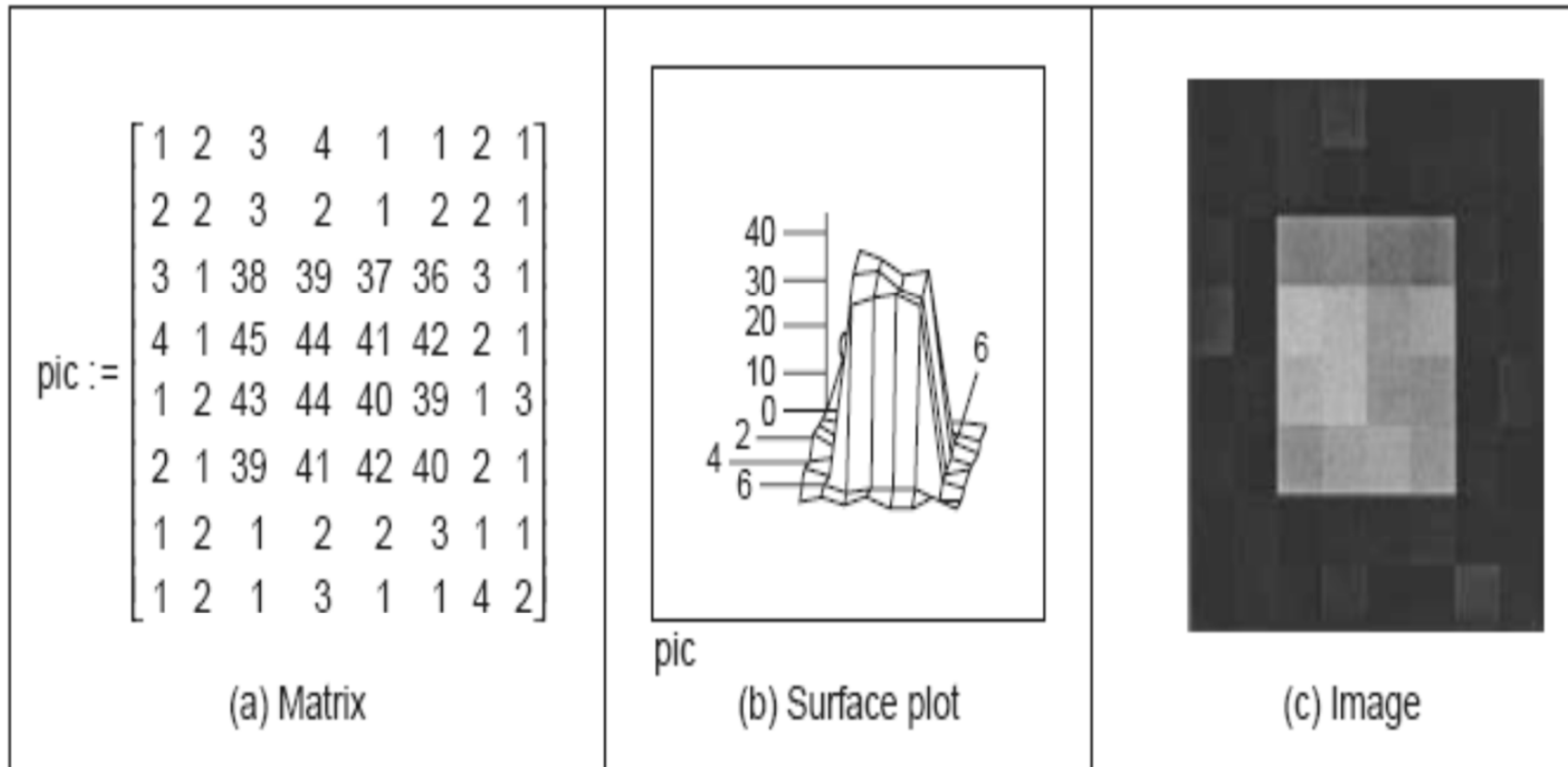


Figure 1.13 Synthesised image of a square

Representing Digital Images

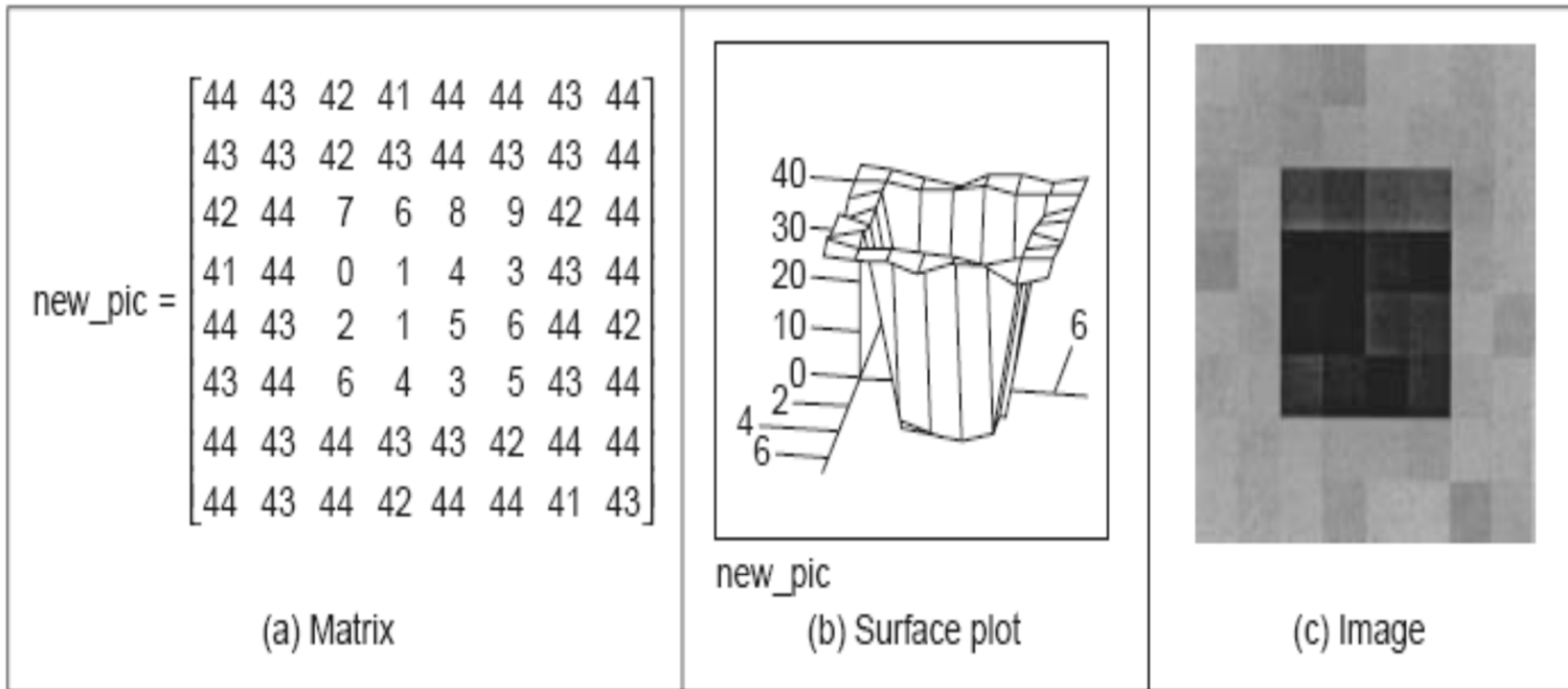


Figure 1.14 Image of a square after inversion

Dealing with Images



Color

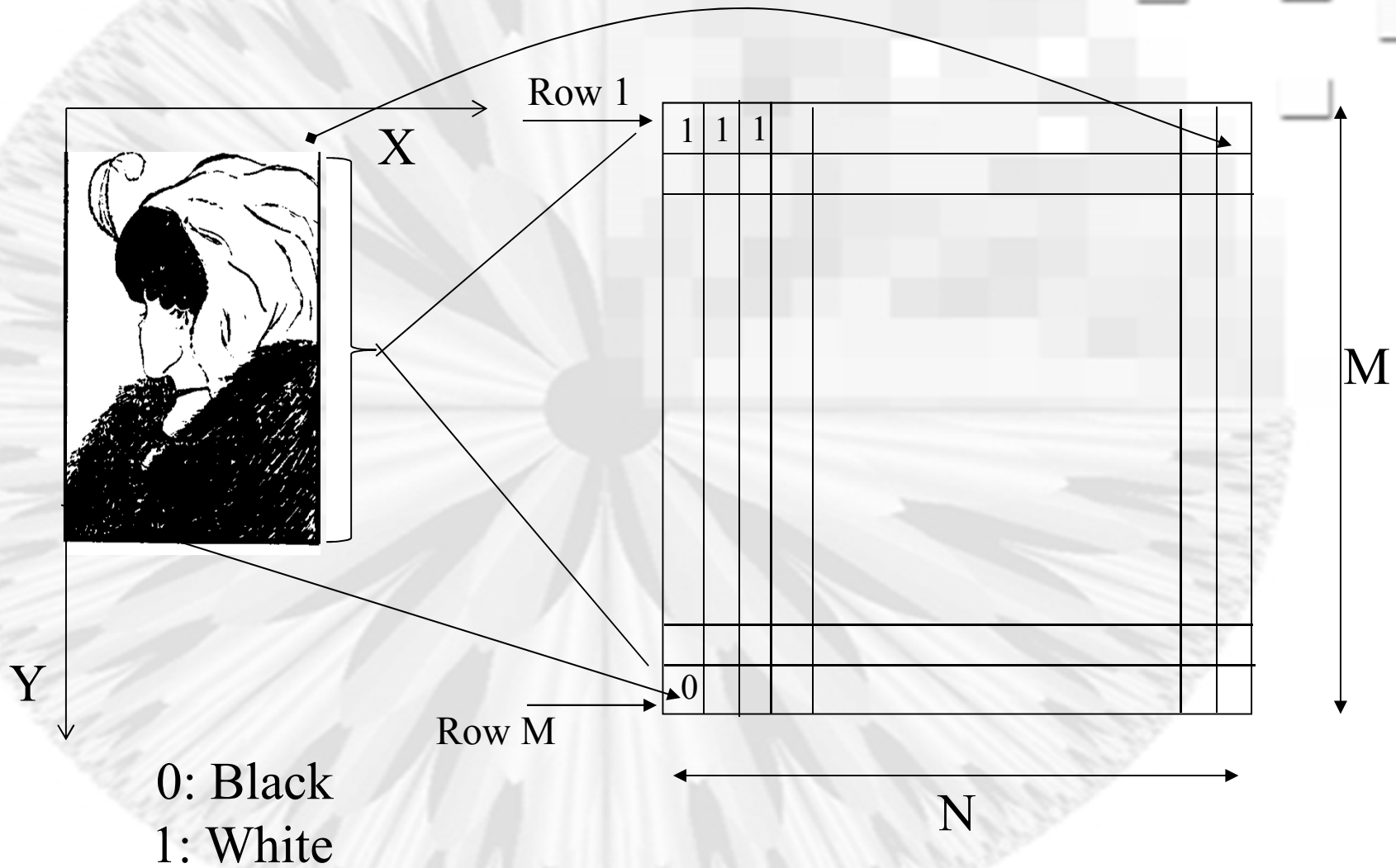


Gray Scale



Binary

Binary Image



A Simple Image Formation Model

The term image refers to a two-dimensional light-intensity function, denoted by $f(x, y)$, where the value or amplitude of f at spatial (time) coordinates (x, y) give the intensity (brightness) of the image at that point.

Since light is a form of energy, $f(x, y)$ must be nonzero and finite, that is,

$$0 < f(x, y) < \infty$$

A Simple Image Formation Model (cont.)

The basic nature of $f(x, y)$ may be considered as being characterized by two components.

- 1. Illumination $I(x, y)$, which is the amount of source light incident on the scene being viewed, and**
- 2. Reflectance $r(x, y)$, which is the amount of light reflected by the objects in the scene.**

A Simple Image Formation Model (cont.)

- The function $I(x,y)$ and $r(x,y)$ combine as a product to form $f(x,y)$

$$f(x,y) = I(x,y)*r(x,y),$$

Where :

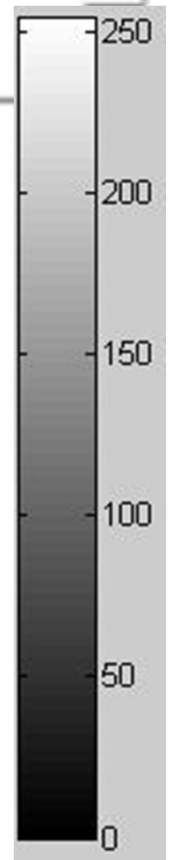
- $0 < I(x,y) < \infty$, and
- $0 < r(x,y) < 1$,
- 0 (total absorption) and 1 (total reflectance).

The nature of $I(x,y)$ is determined by the light source, while $r(x,y)$ determined by the characteristics of the objects.

Gray Scale Image



10	5	9								
									100	



Gray Scale Image

- Each element of the array is referred to as an image element, or picture element, or pixel.
- The term's " image " and " pixels " will be used to denote a digital image and its elements.
- The above digitization process requires that a decision be made on a value for N as well as on the number of discrete levels (L) allowed for each pixel.
- It is common practice in digital image processing to let these quantities be integer powers of two, that is,
$$N = 2^n, \quad M = 2^m \quad L = 2^k.$$
- The number , b , of bits required to store a digitized image is given by : $b = M \times N \times k.$

Gray Scale Image

Example:

A 128x128 image with 64 gray levels requires 98,304 bits of storage. Calculation number of bits as:

$$M = 128$$

$$N = 128$$

$$L = \text{gray level} = 64 = 2^k, \text{ then } k = 6 \text{ (} 64 = 2^6 \text{)}$$

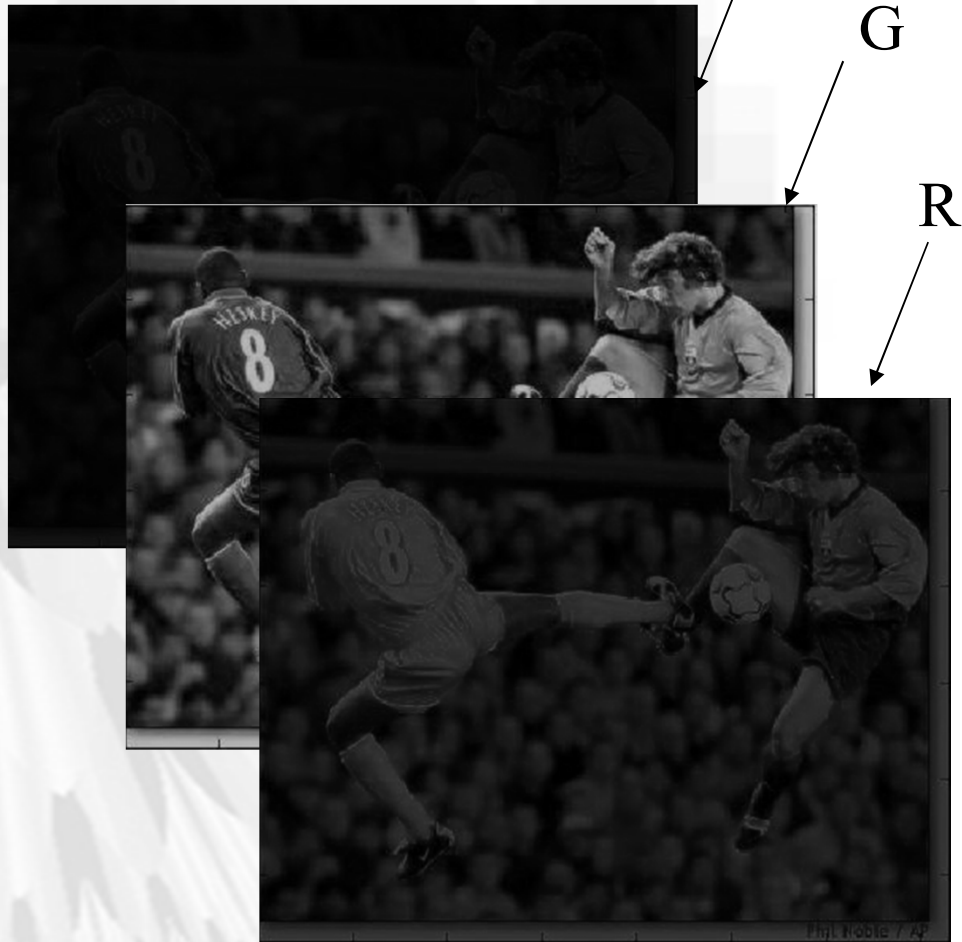
Then

$$P = M \times N \times k = 128 \times 128 \times 6 = 98,304.$$

Color Image (RGB)



Phil Noble / AP



Problem 2.9 page 72 in text book

A common measure of transmission for digital data is the **baud rate**, defined as : **the number of bits transmitted per second**. Generally, transmission is accomplished in packets consisting of a **start bit**, a byte (8 bits) of information, and a stop bit. Using these facts, answer the following:

- (a) How many minutes would it take to transmit a 1024×1024 image with 256 gray levels using a 56K baud modem?
- (b) What would the time be at 750K baud, a representative speed of a phone DSL (digital subscriber line) connection?

Solution:

- (a) The total amount of data (including the start and stop bit) in an 8bit, 1024 x1024 image, is
- **$(1024 \times 1024) \times [8 + 2]$ bits.**
- The total time required to transmit this image over a At 56K baud link is
- **$(1024 \times 1024) \times [8 + 2]/56000 = 187.246$ sec or about **3.12 min.****
- (b) At 750K this time goes down to about = **$(1024)^2 \times [8 + 2]/750000 = 14$ sec.**

The Resolution

- **The resolution(i.e, the degree of details) of an image is strongly dependent on both M, N and k.**
- **The more these parameters are increased, the closer the digitized array will approximate the original image.**

Spatial and Gray-Level Resolution

- **Sampling** is the principal factor determining the *spatial resolution* of an image.
- **Spatial resolution** is the smallest discernible detail in an image.
- **Gray-level resolution** similarly refers to the smallest discernible change in gray level.

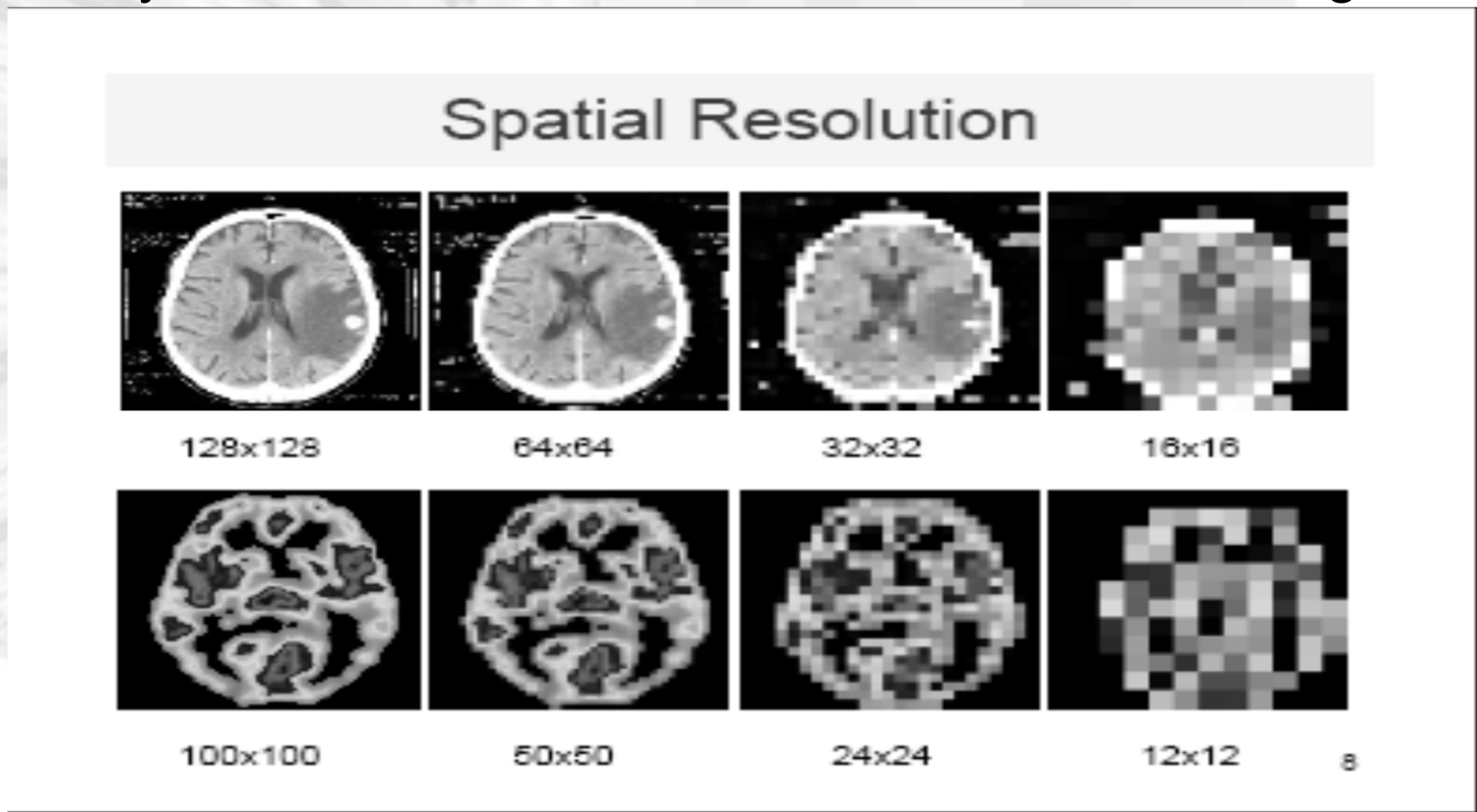
Spatial and Gray-Level Resolution

- **Figure 2.19 shows** an image of size 1024×1024 pixels whose gray levels are represented by 8 bits. The other images are the results of sub sampling the 1024×1024 image. The sub sampling was accomplished by deleting the appropriate number of rows and columns from the original image.
- **For example**, the 512×512 image was obtained by deleting every other row and column from the 1024×1024 image.

Spatial Resolution

The spatial resolution of an image is The physical size of a pixel in an image.

Basically it is the smallest discernable detail in an image.



Quantization

- **N** is usually an integral power of two
- **k** is the number of bits used for quantization
- Typically $k = 8$ $L = 256$ possible gray levels.
- If **k=1**, then there are only two values: 0 and 1
This image is known as a **BINARY** image.
- Sometimes the range of values spanned by the gray levels is called the **dynamic range** of an image.

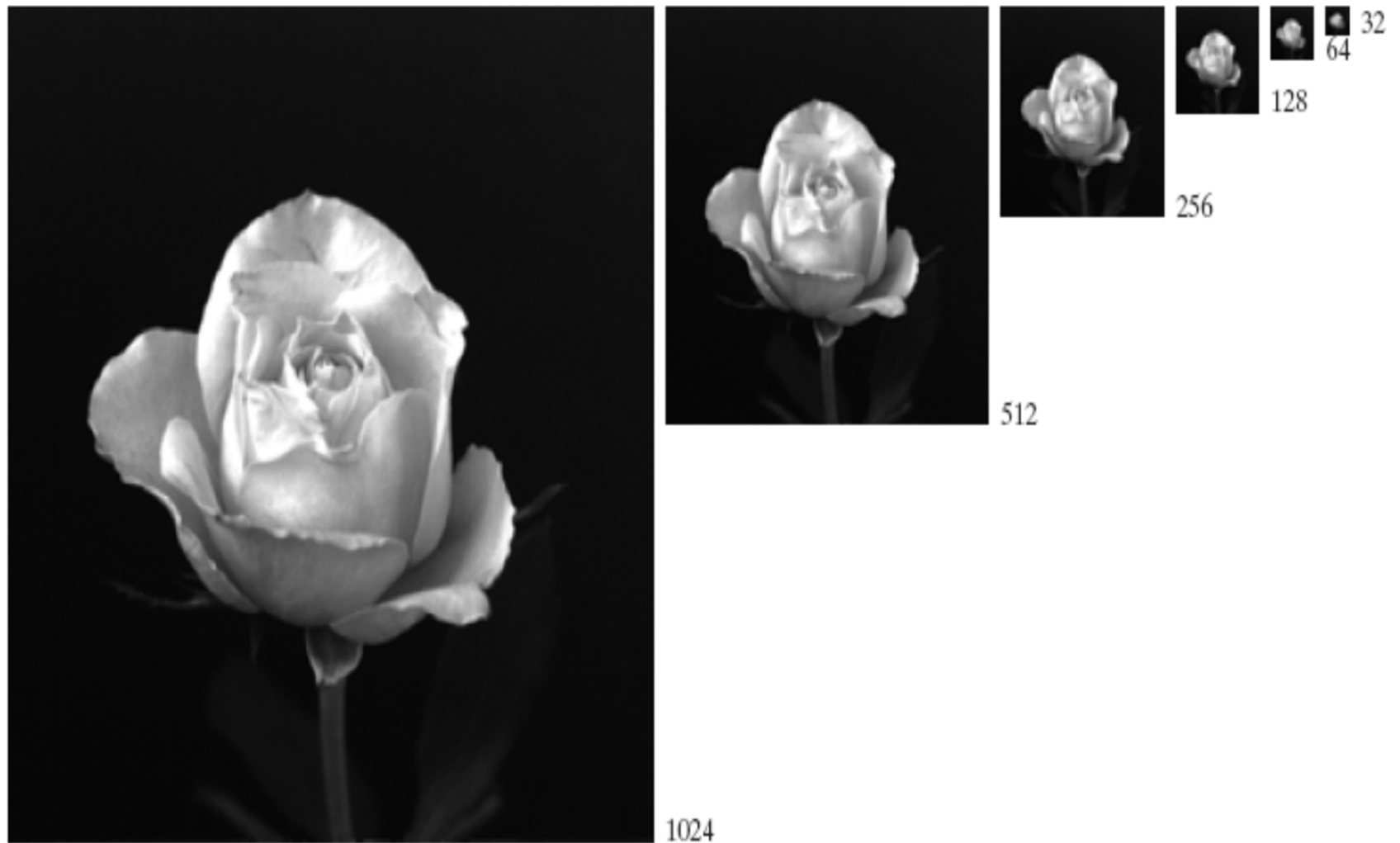
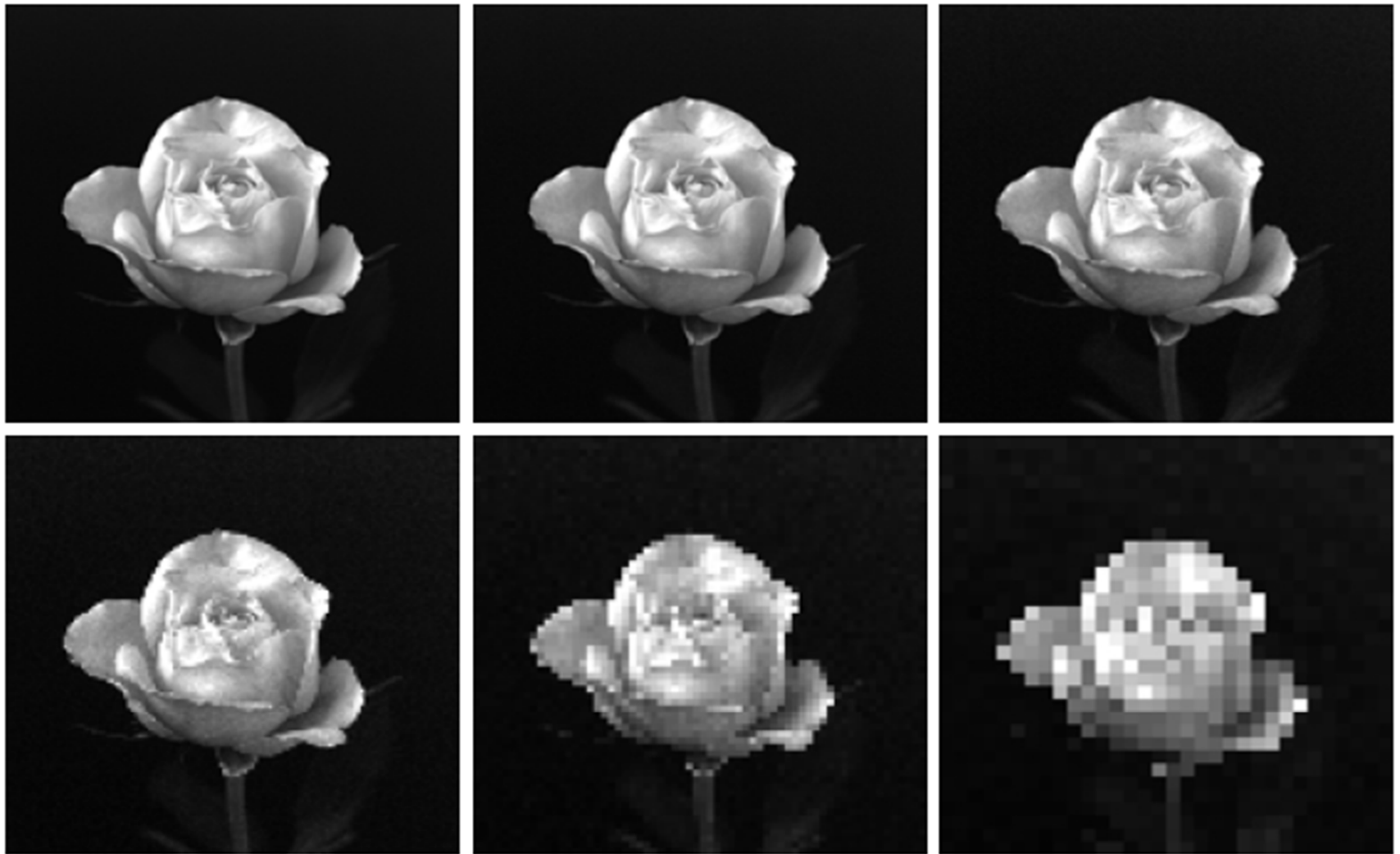


FIGURE 2.19 A 1024×1024 , 8-bit image subsampled down to size 32×32 pixels. The number of allowable gray levels was kept at 256.



a	b	c
d	e	f

FIGURE 2.20 (a) 1024×1024 , 8-bit image. (b) 512×512 image resampled into 1024×1024 pixels by row and column duplication. (c) through (f) 256×256 , 128×128 , 64×64 , and 32×32 images resampled into 1024×1024 pixels.